

Robotics Internship with Accommodation at Kolkata

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Active Categories

5

Focused Areas

Kolkata

Accommodation Location

How to View Accommodation Details and Booking Options

1. Open the Internships page or the corresponding Topics page.
2. Select the relevant focused area.
3. Select the available duration, mode and internship type.
4. Choose **Offline** mode to access accommodation booking options.
5. Continue to the fee/payment page and use the **Branches Select Option**.
6. After selecting the branch, use **Book NTHRYS Accommodation** to view accommodation fee, facility photographs, amenities and the available booking details.

Robotics Internship Categories

AI Robot Perception Research https://internships.nthrys.com/robotics/ai-robot-perception-research	Machine Learning Robot Learning Research https://internships.nthrys.com/robotics/machine-learning-robot-learning-res
AI Motion Planning Research https://internships.nthrys.com/robotics/ai-motion-planning-research	AI Soft Robotics Research https://internships.nthrys.com/robotics/ai-soft-robotics-res
AI Multi-Robot Systems Research https://internships.nthrys.com/robotics/ai-multi-robot-systems-research	AI Manipulation & Grasping Research https://internships.nthrys.com/robotics/ai-manipulation-grasping-research
AI Robot Navigation Research https://internships.nthrys.com/robotics/ai-robot-navigation-research	AI Legged Robot Research https://internships.nthrys.com/robotics/ai-legged-robot-research
AI Human-Robot Trust Research https://internships.nthrys.com/robotics/ai-human-robot-trust-research	AI Field Robotics Research https://internships.nthrys.com/robotics/ai-field-robotics-research
Robot Vision System Development https://internships.nthrys.com/robotics/robot-vision-system-development	Autonomous Drone Flight Control https://internships.nthrys.com/robotics/autonomous-drone-flight-control

Robotic Arm Kinematics Research https://internships.nthrys.com/robotics/robotic-arm-kinematics-research	Sensor Fusion Integration Systems https://internships.nthrys.com/robotics/sensor-fusion-integration-systems
Real-time Path Planning Algorithms https://internships.nthrys.com/robotics/real-time-path-planning-algorithms	Swarm Robotics Coordination Research https://internships.nthrys.com/robotics/swarm-robotics-coordination-research
Deep Learning Vision Models https://internships.nthrys.com/robotics/deep-learning-vision-models	Robot Gripper Design Optimization https://internships.nthrys.com/robotics/robot-gripper-design-optimization
Simultaneous Localization Mapping https://internships.nthrys.com/robotics/simultaneous-localization-mapping	Humanoid Robot Balance Control https://internships.nthrys.com/robotics/humanoid-robot-balance-control
Reinforcement Learning Robot Training https://internships.nthrys.com/robotics/reinforcement-learning-robot-training	Collaborative Robot Safety Systems https://internships.nthrys.com/robotics/collaborative-robot-safety-systems
Underwater Robot Propulsion Research https://internships.nthrys.com/robotics/underwater-robot-propulsion-research	Computer Vision Pose Estimation https://internships.nthrys.com/robotics/computer-vision-pose-estimation
Robot Motion Capture Systems https://internships.nthrys.com/robotics/robot-motion-capture-systems	Wheeled Robot Traction Dynamics https://internships.nthrys.com/robotics/wheeled-robot-traction-dynamics
Semantic Scene Understanding https://internships.nthrys.com/robotics/semantic-scene-understanding	Robot Task Planning Architecture https://internships.nthrys.com/robotics/robot-task-planning-architecture
Aerial Manipulation Research https://internships.nthrys.com/robotics/aerial-manipulation-research	Tactile Sensing Integration https://internships.nthrys.com/robotics/tactile-sensing-integration
Robot Localization GPS-denied https://internships.nthrys.com/robotics/robot-localization-gps-denied	Automated Robot Calibration Methods https://internships.nthrys.com/robotics/automated-robot-calibration-methods
Biologically-inspired Robot Locomotion https://internships.nthrys.com/robotics/biologically-inspired-robot-locomotion	Predictive Collision Avoidance Systems https://internships.nthrys.com/robotics/predictive-collision-avoidance-systems
Robot Grasp Quality Metrics https://internships.nthrys.com/robotics/robot-grasp-quality-metrics	Drone Swarm Cooperative Mapping https://internships.nthrys.com/robotics/drone-swarm-cooperative-mapping
Neural Network Robot Control https://internships.nthrys.com/robotics/neural-network-robot-control	Wheeled-legged Hybrid Robots https://internships.nthrys.com/robotics/wheeled-legged-hybrid-robots
Object Detection Real-time Systems https://internships.nthrys.com/robotics/object-detection-real-time-systems	Robot Dexterous Hand Control https://internships.nthrys.com/robotics/robot-dexterous-hand-control
Visual Servoing Control Methods https://internships.nthrys.com/robotics/visual-servoing-control-methods	Quadrotor Trajectory Optimization https://internships.nthrys.com/robotics/quadrotor-trajectory-optimization
Force Control Robotic Assembly https://internships.nthrys.com/robotics/force-control-robotic-assembly	3D Scene Reconstruction Methods https://internships.nthrys.com/robotics/3d-scene-reconstruction-methods
Mobile Manipulation Integrated Systems https://internships.nthrys.com/robotics/mobile-manipulation-integrated-systems	Semantic Mapping Robot Environments https://internships.nthrys.com/robotics/semantic-mapping-robot-environments
Snake-like Robot Locomotion https://internships.nthrys.com/robotics/snake-like-robot-locomotion	Attention Mechanisms Robot Vision https://internships.nthrys.com/robotics/attention-mechanisms-robot-vision
Parallel Gripper Jaw Control https://internships.nthrys.com/robotics/parallel-gripper-jaw-control	Terrain Classification Mobile Robots https://internships.nthrys.com/robotics/terrain-classification-mobile-robots

Robotics Internship Topics and Focused Areas

Autonomous Drone Flight Control

- Vision-Based Autonomous Navigation

- Flight Control System Design and Optimization
- Multi-Agent Drone Coordination and Swarm Control
- Path Planning and Obstacle Avoidance Algorithms
- Sensor Fusion and State Estimation for Autonomous Flight

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